

# Transverter

The Transverter driver implements communication with devices compatible with the Transverter library. The communications blocks are dynamically created according to the pooling cycle defined on the AccessType for each Device Point.

## Summary Information

**Communication Driver Name:** Transverter

**Current Version:** 1.1

**Implementation DLL:** T.ProtocolDriver. Transverter.dll

**Protocol:** Transverter

**Interface:** Transverter library

**PLC types supported:** Any equipment compatible with the Transverter library

**PC Hardware requirements:** Raspberry PI

**Supported Equipment:** T13x and HT2000

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## Point Configuration

The syntax for the Transverter communication points is: <Equipment>:<Property>:<Line/Relay/Module>

Where:

- **<Equipment>** = T13x or HT2000
- **<Property>** = LineCurrent, LineFrequency, etc. [See the Transverter Library manual]
- **<Line/Relay/Module>** = Optional number [See the Transverter Library manual]

Ex: T13x: LineFrequency, HT2000:MaxV190:0

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## Troubleshoot

The status of the driver's execution can be observed through the diagnostic tools, which are:

- Trace window
- Property Watch
- Module Information

The above tools indicate if the operations have succeeded or have failed. A status of 0 (zero) means communication is successful. Negative values indicate internal driver errors.