

Bosch Rexroth – IndraControl Devices Using EtherNet/IP Adapter

The IndraControl communication driver implements communication with Bosch Rexroth IndraControl L20/L40 PLCs using a EtherNet/IP adapter.

Summary Information

Communication Driver Name: IndraControl

Implementation DLL: T.ProtocolDriver.IndraControl.dll

Manufacturer: Bosch Rexroth

Protocol: EtherNet/IP - Bosch

PLC Types Supported: Bosch Rexroth IndraControl L20/L40

Interface: TCP/IP

Supported Data:

| Type | Read | Write | Data Type |
|-----------------------------|------|-------|-----------|
| EtherNet/IP Adapter Outputs | Yes | Yes | Byte Only |
| EtherNet/IP Adapter Inputs | Yes | | Byte Only |

Channel Configuration

Protocol Options

None

Node Configuration

Station Configuration

Stations syntax: <IP>;<Port>;

Where :

- <IP> = The IP address of the slave device in the network
- <Port> = The TCP port where the slave device is listening (default is 44818)

Sample Node configuration

| Name | Channel | Primary Station |
|--------------|--------------|-----------------------|
| IndraControl | IndraControl | 192.168.200.105;44818 |

Point Address Configuration

The syntax for the IndraControl communication points is: <%QB><Address> for Outputs and <%IB><Address> for inputs

E.g.: %QB1 (Type = Output, Address = 1)

Sample Points Configuration

| TagName | Node | Address | DataType | AccessType |
|----------|--------------|---------|----------|------------|
| Output1 | IndraControl | %QB1 | Native | ReadWrite |
| Output2 | IndraControl | %QB2 | Native | ReadWrite |
| Output3 | IndraControl | %QB3 | Native | ReadWrite |
| Output15 | IndraControl | %Q15 | Native | ReadWrite |
| Input1 | IndraControl | %IB1 | Native | Read |
| Input1 | IndraControl | %IB2 | Native | Read |

Troubleshoot

The status of the driver's execution can be observed through the diagnostic tools, which are:

- Trace window
- Property Watch
- Module Information

The above tools indicate if the operations have succeeded or have failed. A status of 0 (zero) means communication is successful. Negative values indicate internal driver errors, and positive values indicate protocol error codes.